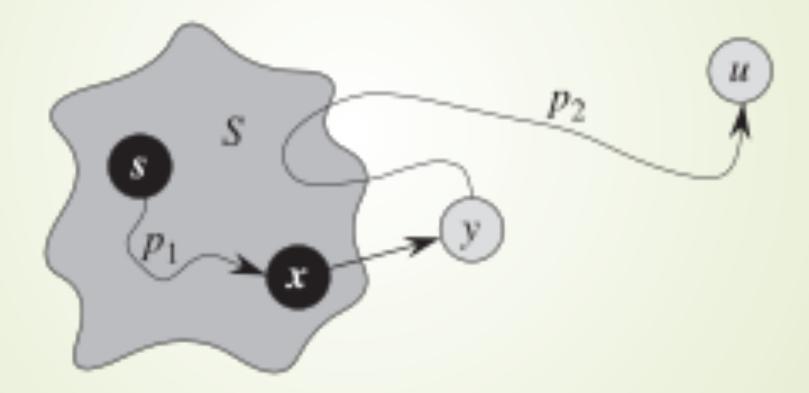
COT 5407: Introduction to Algorithms Giri NARASIMHAN

www.cs.fiu.edu/~giri/teach/5407S19.html

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² Correctness of Dijkstra's Alg



Analysis of Dijkstra's Algorithm

O(n) calls to INSERT, EXTRACT-MIN O(m) calls to DECREASE-KEY

| Approach | Insert | Dec-Key | Extract-Min | Total |
|-----------------|----------|----------|-------------|--------------------|
| PQ in Arrays | O(1) | O(1) | O(n) | O(n ²) |
| Heaps | O(log n) | O(log n) | O(log n) | O((m+n)log n) |
| Fibonacci Heaps | O(1)* | O(1)* | O(log n)* | O(m + n log n)* |

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3

* Amortized Time Complexity

4 SSSP Algorithms

- Dijkstra's algorithm (only non-negative edges allowed)
 - Best: O(m + n log n)
- Bellman-Ford algorithm (allows non-negative edges, but less efficient)
 - Repeated RELAX steps until we have answers
 - O(mn) time complexity

⁵ All Pairs Shortest Path Algorithm

Need to find shortest paths (or length) between every pair of vertices

- Invoke Dijkstra's SSSP algorithm n times.
- Or an alternative approach ...

Structure of a Shortest Path

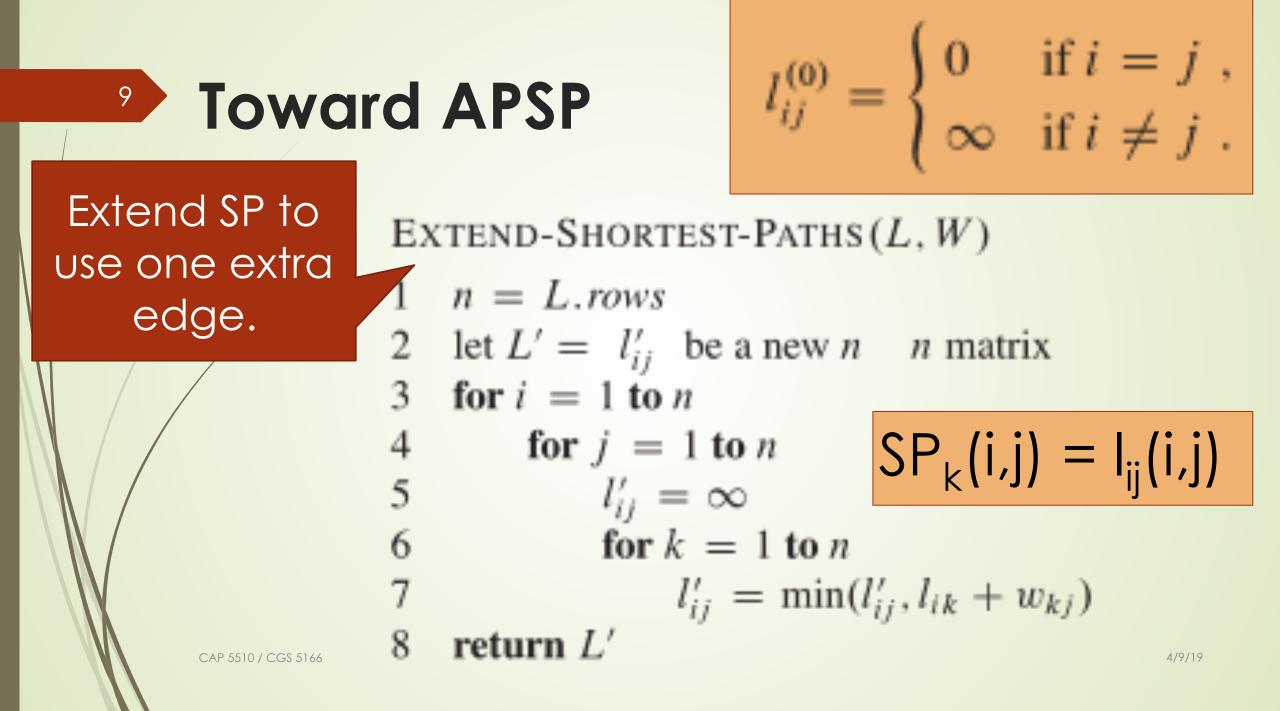
- Optimal substructure property
 - Every subpath of a shortest path is "optimal", i.e., it is a shortest path between the relevant vertices.
- Can we use DP?
 - Invent appropriate subproblems to cast it as a DP



- In iteration k, find SP_k(u,v), shortest paths between u and v that use at most k edges
- Iteration 1: find all shortest paths that use at most 1 edge
 - Every edge (u,v) is a SP between u and v
 - Every non-edge (u,v) means no SP exists between u and v using at most one edge

⁸ Iteration k

- We already have SP_{k-1}(u,v) from iteration k-1
 - If path of length k between u & v exists, then path of length k-1 exists between u and a neighbor of v
 - SP_k(u,v) can be computed as follows:
 - $SP_k(u,v) = min (SP_{k-1}(u,v), min_w {SP_{k-1}(u,w) + SP_1(w,v)})$
 - This is our recurrence relation



APSP Algorithm

SLOW-ALL-PAIRS-SHORTEST-PATHS(W) n = W.rows $L^{(1)} = W$ for m = 2 to n = 1let $L^{(m)}$ be a new n - n matrix $L^{(m)} = \text{EXTEND-SHORTEST-PATHS}(L^{(m-1)}, W)$ return $L^{(n-1)}$

O(n4) time complexity

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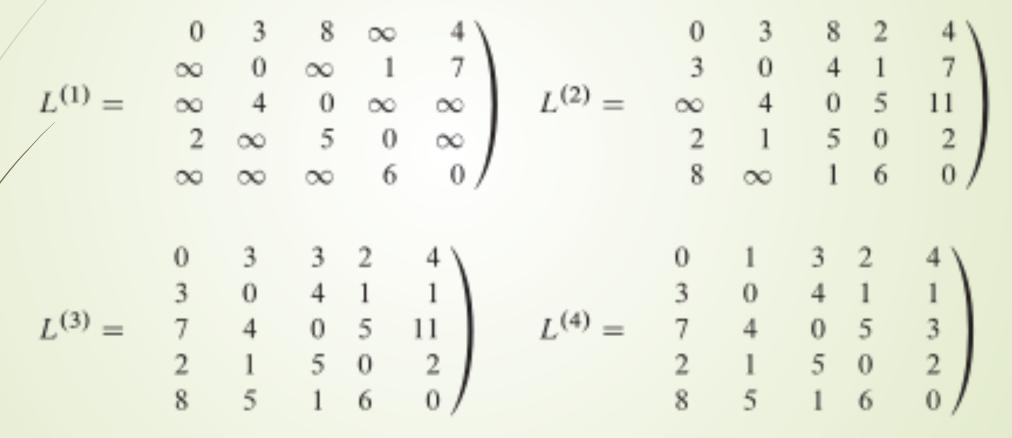
11 **APSP Algorithm – Matrix Mult**

EXTEND-SHORTEST-PATHS(L, W)n = L.rowslet $L' = l'_{ii}$ be a new *n n* matrix 2 let *C* be a new *n n* matrix for i = 1 to n for j = 1 to n $l'_{ii} = \infty$ for k = 1 to n6 $l'_{ij} = \min(l'_{ij}, l_{ik} + w_{kj})$ 8 return L'

SQUARE-MATRIX-MULTIPLY (A, B)

 $1 \quad n = A$, rows 3 for i = 1 to nfor j = 1 to n $c_{ij} = 0$ for k = 1 to n $c_{ij} = c_{ij} + a_{ik} b_{kj}$ 8 return C

Intermediate Matrices ...

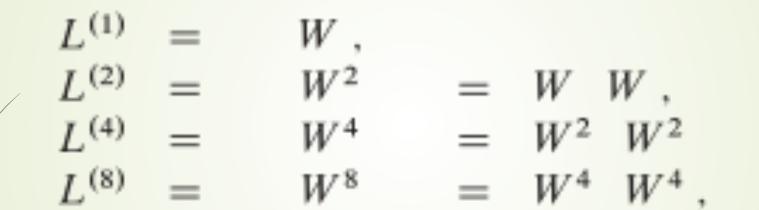


Improved Idea

FASTER-ALL-PAIRS-SHORTEST-PATHS(W) n = W.rows $L^{(1)} = W$ m = 1while m < n = 1let $L^{(2m)}$ be a new n - n matrix $L^{(2m)} = \text{EXTEND-SHORTEST-PATHS}(L^{(m)}, L^{(m)})$ 6 m = 2mreturn L^(m) 8 O(n³log n) time complexity

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Repeating Squaring Idea



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 $L^{(2^{\lceil \lg(n-1) \rceil})} = W^{2^{\lceil \lg(n-1) \rceil}} = W^{2^{\lceil \lg(n-1) \rceil - 1}} W^{2^{\lceil \lg(n-1) \rceil - 1}}.$

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Floyd-Warshall's Algorithm

- SP_k(u,v), shortest paths between u and v that use at most k edges
- Old definition

- SP_k(u,v), shortest paths between u and v that uses intermediate vertices from {1,2,...,k}
- New definition

Recurrence Relation

Old Relation

SP_k(u,v) = min (SP_{k-1}(u,v), min_w {SP_{k-1}(u,w) + SP₁(w,v)})

New Relation

• $SP_k(u,v) = min(SP_{k-1}(u,v), SP_{k-1}(u,k) + SP_{k-1}(k,v))$

Floyd-Warshall: Improved APSP

17

FLOYD-WARSHALL(W) $1 \quad n = W.rows$ O(n³) time complexity $D^{(0)} = W$ for k = 1 to nlet $D^{(k)} = d_{ii}^{(k)}$ be a new n *n* matrix 4 for i = 1 to n 6 for j = 1 to n $d_{ij}^{(k)} = \min d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{ki}^{(k-1)}$ CAP 5510 / CGS 5165 return $D^{(n)}$ 4/9/19

$$\begin{split} D^{(0)} &= \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad \Pi^{(0)} &= \begin{pmatrix} \text{NIL} & 1 & 1 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & \text{NIL} \\ 4 & \text{NIL} & 4 & \text{NIL} & \text{NIL} \\ 1 & \text{NIL} & \text{NIL} & \text{NIL} & \text{NIL} \\ 1 & \text{NIL} & \text{NIL} & \text{NIL} & \text{NIL} \\ 1 & \text{NIL} & \text{NIL} & \text{NIL} & \text{NIL} \\ 1 & \text{NIL} & \text{NIL} & \text{NIL} & \text{NIL} \\ 1 & \text{NIL} & \text{NIL} & \text{NIL} & \text{NIL} \\ 1 & \text{NIL} & \text{NIL} & \text{NIL} & \text{NIL} \\ 2 & \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad \Pi^{(1)} &= \begin{pmatrix} \text{NIL} & 1 & 1 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & \text{NIL} & 1 \\ 2 & 1 & 3 & \text{NIL} & \text{NIL} & \text{NIL} \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad \Pi^{(2)} &= \begin{pmatrix} \text{NIL} & 1 & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 1 & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 1 & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 1 & 2 & 2 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & 1 & 1 \\ \text{NIL} & \text{NIL} & 1 & 1 \\ \text{NIL} & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & 2 & 1 \\ \text{NIL} & \text{NIL} & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & 1 & 1 \\ \text{NIL} & \text{NIL} &$$

18

COT 54

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Figure 25.4 The sequence of matrices $D^{(k)}$ and $\Pi^{(k)}$ computed by the Floyd-Warshall algorithm for the graph in Figure 25.1.

2/23/17

Figure 14.38

Worst-case running times of various graph algorithms

| Type of Graph Problem | Running Time | Comments |
|-----------------------------|--------------------|------------------------|
| Unweighted | O(E) | Breadth-first search |
| Weighted, no negative edges | $O(E \log V)$ | Dijkstra's algorithm |
| Weighted, negative edges | $O(E \cdot V)$ | Bellman-Ford algorithm |
| Weighted, acyclic | O(E) | Uses topological sort |